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## RIEMANN'S PROBLEM WITH CONTINUOUS COEFFICIENT

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ABSTRACT: A procedure for solving Riemann's boundary-value problem for the boundary between a multiply-connected region and its complement. Generalization of a result found previously by Gakhov by relaxing the conditions on the given functions. A slight change in one of the given functions does not appreciably change the result, so that a sequence of approximations is possible.

1°. Statement of the problem. Let C denote a contour consisting of m+1 /278\* simple closed contours  $C_0$ ,  $C_1$ , ...,  $C_m$  of the Lyapunov type that bound a connected region  $D^+$ . Its complement with respect to the plane consists of the union of m bounded simply-connected regions  $D^-_k$  (for  $k=1,\ldots,m$ ) and an infinite region  $D^-_0$ . For brevity, we shall refer to this complement as a region and shall denote it by  $D^-$ . Following the general practice, we denote by  $L_p$  (C) the class of functions that are p-summable on the contour C.

We formulate Riemann's problem as follows:

Find functions  $\Phi^{\pm}$  that are analytic\*\* in  $D^{\pm}$ , that have almost everywhere on the contour C limiting angular values  $\Phi^{\pm}$  (t) belonging to  $L_p$  (C) with p > 1, that satisfy the condition  $\Phi^{-}$  ( $\infty$ ) = 0, and that satisfy the boundary condition

$$\Phi^{+}(t) = G(t) \Phi^{-}(t) + g(t), \tag{1}$$

where  $g(t) \in L_{p}(C)$  and G(t) is a continuous function that vanishes nowhere.

As usual, we call the integer  $x = \sum_{k=0}^{\infty} x_k$  where  $x_k = \frac{1}{2\pi} [\arg G(t)]_{C_k}$ , the index of the problem.

We take as positive direction around a boundary of  $D^+$  that direction which puts  $D^+$  on one's left.

<sup>\*</sup>Numbers in the margin indicate pagination in the foreign text.

<sup>\*\*</sup>We consider only functions that can be represented by a Cauchy integral.

Riemann's problem has been solved in closed form by F. D. Gakhov [1] for the case in which G(t) and g(t) satisfy a Hölder condition. B.V. Khvedelidze generalized this solution to the case of a multiply-connected region [2] when g is psummable for p > 1 [3].

In the present article, we show that Gakhov's results dealing with Riemann's problem remain valid when G(t) is assumed merely continuous.

2°. We know that every summable function can be represented in the form

$$\Phi(t) = \Phi^+(t) - \Phi^-(t), \tag{2}$$

where the  $\Phi^{\pm}(t)$  are almost everywhere limiting angular values of functions  $\Phi^{\pm}(z)$  that are analytic in  $D^{\pm}$ . The representation (2) is unique if we assume that  $\Phi^{\pm}(t) \in L_{g}(C)$  (with  $\delta > 0$ ) and  $\Phi^{-}(\infty) = 0$ .

The functions  $\Phi^{\pm}(t)$  are given by Sokhotskiy's formulas

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$$\Phi^{+}(t) = \frac{1}{2} \Phi(t) + \frac{1}{2\pi i} \int_{C} \frac{\Phi(\tau)}{\tau - t} d\tau,$$

$$\Phi^{-}(t) = -\frac{1}{2} \Phi(t) + \frac{1}{2\pi i} \int_{C} \frac{\Phi(\tau)}{\tau - t} d\tau.$$
(3)

The validity of formulas (3) for summable  $\Phi$  was shown by I. I. Privalov [4]. B. V. Khvedelizde [3] showed that membership of  $\Phi(t)$  in the class  $L_p(C)$ , for p>1, implies that  $\Phi^+(t)$  and  $\Phi^-(t)$  belong to  $L_p(C)$  also and that the singular operator  $\frac{1}{\pi i} \int_C \frac{\Phi(\tau)}{\tau - t} d\tau$  is a bounded operator in the norm of the space  $L_p(C)$ , for p>1; that is,  $\left(\int_C \left|\frac{1}{\pi}\int_C \frac{\Phi(\tau)}{\tau - t} d\tau\right| ds\right)^{1/p} \leqslant M_p\left(\int_C |\Phi(t)|^p ds\right)^{1/p}$ , where  $M_p$  is a constant independent of  $\Phi$ . It follows from this that

$$\| \Phi^{\pm} \|_{L_{p}} \leq \frac{1}{2} \| \Phi \|_{L_{p}} + \frac{M_{p}}{2} \| \Phi \|_{L_{p}} = \frac{M_{p}+1}{2} \| \Phi \|_{L_{p}},$$

where

$$\|\Phi\|_{L_p} = \left(\int\limits_C |\Phi(t)|^p ds\right)^{1/p}.$$

This enables us to formulate Riemann's problem in the following form.

Find a function  $\Phi$  belonging to the class  $L_p(c)$  and satisfying the boundary condition (1), where  $\Phi^+$  and  $\Phi^-$  denote the operators defined by equations (3).

Our investigation is based on the following simple idea: If G=1, Riemann's problem reduces to a saltus problem and unconditionally has a unique solution in the class  $L_p$ . It turns out that small deviations in the coefficient G from unity do not change the nature of the solution. This can be proved by the method of

successive approximations. We can shift to the general case choosing a sequence of functions satisfying a Hölder condition that converges to ln G. An analogous device was used by S.G. Mikhlin [5] in his investigation of singular integral equations with Cauchy kernel.

3°. Let us look at the case of Riemann's problem when G(t) is measurable and satisfies the condition

$$|G(t)-1| \leq q < \frac{2}{1+M_{\rho}}, \quad g(t) \in L_{\rho}(C) \quad (\rho > 1).$$

If we subtract  $\Phi^-$  from both sides of (1), we obtain

$$\Phi(t) = [G(t) - 1] \Phi^{-}(t) + g(t). \tag{4}$$

Note that

$$\|[G(t)-1] \Phi^-\|_{L_p} = \left( \int_C |G(t)-1|^p |\Phi^-|^p ds \right)^{1/p} \le$$

$$\le q \left( \int_C |\Phi^-|^p ds \right)^{1/p} = q \frac{1+M_p}{2} \|\Phi\|_{L_p}.$$

Applying the principle of contraction mappings, we see that the problem (4) (and consequently (1)) necessarily has a unique solution.

4°. The case  $\kappa_0 = \kappa_1 = \dots = \kappa_m = 0$ . In this case,  $\ln G$  is a continuous  $\frac{\sqrt{280}}{1}$  function. Let us approximate it with a function f that satisfies a Hölder condition and that satisfies the inequality

$$|e^{(\ln Q - I)} - 1| \leqslant q < \frac{2}{1 + M_p}.$$
 (5)

Furthermore, by using Gakhov's method, we can represent the function  $G_1(t) = e^f$  in the form of a ratio  $G_1(t) = X^+(t)/X^-(t)$ , where the  $X^{\pm}$  are functions that are analytic in the regions  $D^{\pm} + C$ , and nonzero everywhere.

Let us introduce new functions  $\Phi_1^{\pm} = \Phi^{\pm} [X]^{-1}$ , in terms of which the problem (1) can be written as follows:

$$\Phi_1^+ = \frac{G}{G_1} \Phi_1^- + \frac{g}{X^+}. \tag{6}$$

By virtue of condition (5), the coefficient  $GG_1^{-1}$  satisfies the requirements of section 3°. Therefore, the problem (6) and, hence, the problem (1) in the case  $\varkappa_0 = \varkappa_1 = \ldots = \varkappa_m = 0$  necessarily has a unique solution.

- 5°. Let us now investigate the most general case.
- a)  $\kappa = 0$ . Introducing the new unknown functions

$$\Phi_{*}^{+}(z) = \prod_{k=1}^{m} (z - z_{k})^{\kappa_{k}} \Phi^{+}(z), \quad \Phi_{*}^{-}(z) = \Phi^{-}(z) \quad (z_{k} \in D_{k}^{-}),$$

we arrive at the problem

$$\Phi_*^+ = G^* \Phi_*^- + g^*, \tag{7}$$

where

$$G^*(t) = \prod_{k=1}^m (t-z_k)^{x_k} G(t), \quad g^*(t) = \prod_{k=1}^m (t-z_k)^{x_k} g(t).$$

We note that

$$x_k^* = \frac{1}{2\pi} [\arg G^*]_{C_k} = 0, \quad k = 1, ..., m; \quad x_0^* = \frac{1}{2\pi} [\arg G^*]_{C_0} = x = 0.$$

Therefore, on the basis of the results of section  $4^{\circ}$ , we conclude that the problem (6), and hence problem (1) in the case  $\varkappa = 0$  have a unique solution.

b)  $\kappa > 0$ . Let us write the problem (1) in the following form:

$$(t-z_0)^{-\kappa}\Phi^+(t)-(t-z_0)^{-\kappa}P_{\kappa-1}(t)=$$

$$=(t-z_0)^{-\kappa}G(t)\Phi^-(t)+(t-z_0)^{-\kappa}g(t)-(t-z_0)^{-\kappa}P_{\kappa-1}(t),$$

where  $z_0 \in D^+$ ;  $P_{\varkappa-1}$  is a polynomial of degree not exceeding  $\varkappa-1$ , chosen in such a way that the function  $(z-z_0)^{-\varkappa} [\Phi^+(z)-P_{\varkappa-1}(z)]$  does not have a pole at the point  $z_0$ . We note that Ind  $(t-z_0)^{-\varkappa} G = 0$ . We denote by  $R^+$  an operator solving Riemann's problem with coefficient  $(t-z_0)^{-\varkappa} G$ . Then we have

$$(t-z_0)^{-\kappa} \left[\Phi^+(t) - P_{\kappa-1}(t)\right] = R^+ \left[\left(g(t) - P_{\kappa-1}(t)\right) (t-z_0)^{-\kappa}\right],$$

$$\Phi^-(t) = R^- \left[\left(g(t) - P_{\kappa-1}(t)\right) (t-z_0)^{-\kappa}\right].$$
(8)

We find  $\Phi^+$  from the first equation:

$$\Phi^{+}(t) = P_{n-1}(t) + (t-z_0)^{n} R^{+} [(g(t) - P_{n-1}(t))(t-z_0)^{-n}].$$
 (9)

We have shown that the solution of the problem (1) must be of the form (8) or (9). However, one can easily see that, for an arbitrary polynomial  $P_{\kappa-1}$ , formulas (8) and (9) yield the general solution of the problem.

c)  $\kappa < 0$ . We write the problem (1) in a different form:

$$\Phi^+(t) (t-z_0)^{-\kappa} = G(t) (t-z_0)^{-\kappa} \Phi^-(t) + g(t) (t-z_0)^{-\kappa}$$

Obviously, Ind  $(t - z_0)^{-\mathcal{H}}$  G(t) = 0 and  $(t - z_0)^{-\mathcal{H}} \Phi^+$  (t) is analytic in  $D^+$ . If we again denote by  $R^{\pm}$  an operator that solves Riemann's problem with coefficient

 $(t - z_0)^{-\kappa}$  G, we obtain

$$\Phi^{+}(z) = (z - z_0)^{\times} R^{+} [(t - z_0)^{-\times} g(t)], \tag{10}$$

$$\Phi^{-}(z) = R^{-}[(t - z_0)^{-\kappa} g(t)]. \tag{11}$$

The function defined by the expression (10) has, in general, a pole of order  $|\varkappa|$  at the point  $z_0$ . Therefore, for the problem posed to have a solution,  $|\varkappa|$  solvability conditions must be satisfied:

$$\int_{R} (t-z_0)^{-k} R^+[g(t)(t-z_0)^{-k}] dt = 0.$$
 (12)

When (12) is satisfied, the problem has a unique solution.

Summarizing the results of section 5°, we have:

Theorem. a) In the case  $\kappa=0$ , Riemann's boundary problem has a unique solution.

- b) In the case  $\kappa > 0$ , the problem is always solvable, and its general solution has  $\kappa$  linearly independent components.
- c) In the case  $\kappa < 0$ , the problem has a solution only when  $\kappa$  solvability conditions  $s_k = 0$  are satisfied, where the  $s_k$  are linearly independent functionals. When these conditions are satisfied, the problem has a unique solution.

In conclusion, I wish to express my deep gratitude to F.D. Gakhov, who supervised the work, and to V.V. Ivanov for useful criticism of it.

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